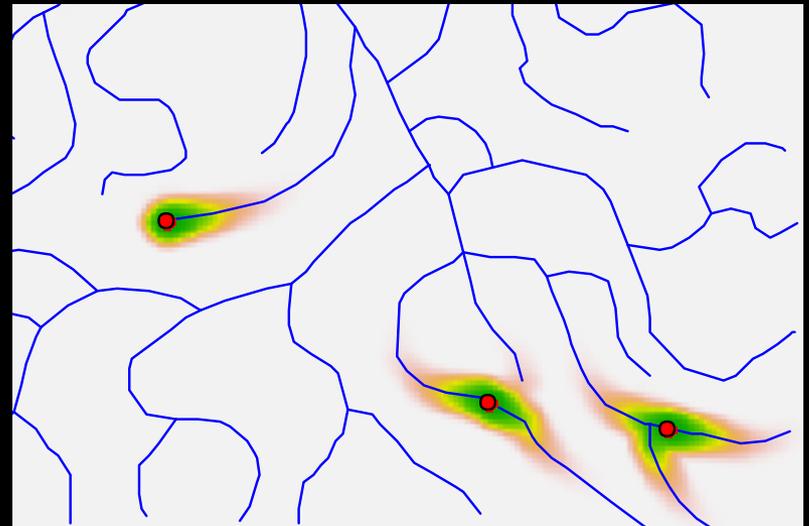


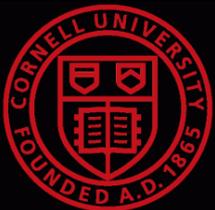
Measuring 'ecological' distance in spatial capture-recapture models

Chris Sutherland, Angela Fuller & Andy Royle

American mink in riparian corridors



*The views expressed in these slides are that
of the author only.*



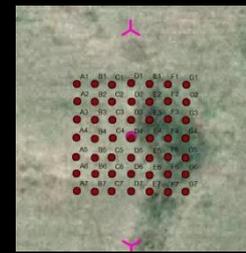
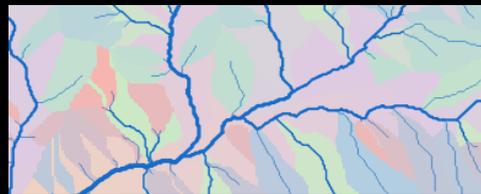
Spatial Capture-Recapture (SCR)

Acknowledges the inherent spatially nature of ecological processes and observation processes:

- effective area sampled \sim *absolute* density
- heterogeneous encounter probabilities

but, useful for many other challenges in ecological research:

- movement, space-use, resource selection, survival, recruitment



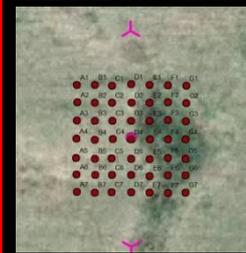
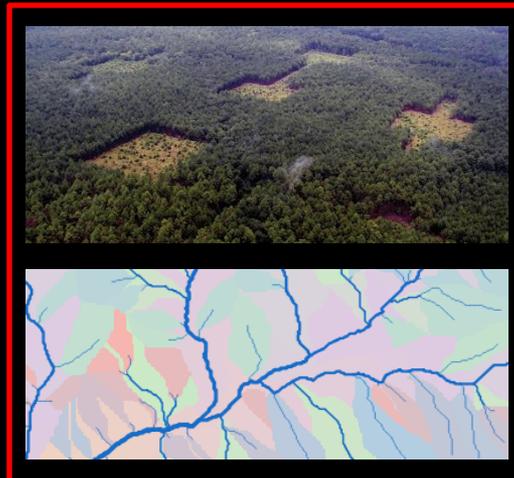
Spatial Capture-Recapture (SCR)

Acknowledges the inherent spatially nature of ecological processes and observation processes:

- effective area sampled \sim *absolute* density
- heterogeneous encounter probabilities

but, useful for many other challenges in ecological research:

- movement, space-use, resource selection, survival, recruitment, *connectivity/landscape resistance* (Royle *et al.*, 2013)



Spatial Capture-Recapture (SCR)

Retaining the spatial information about trap locations and therefore about individual encounter locations:

Non-spatial encounter history

$$y_{i,k} = [y_{i,1,k} \ y_{i,2,k} \ \dots \ y_{i,J,k}]$$

Y =

| | | | | |
|----------------|---|-----------|---|---|
| | | visit (k) | | |
| | | | 1 | 1 |
| | | 1 | 0 | 1 |
| | | 0 | 0 | 1 |
| | | 0 | 0 | 0 |
| | | 1 | 0 | 1 |
| | | 0 | 1 | |
| | | 1 | | |
| individual (i) | ↓ | | | |

Caught in any trap

Spatial encounter history

$$y_{i,k} = [y_{i,1,k} \ y_{i,2,k} \ \dots \ y_{i,J,k}]$$

Y =

| | | | | | | | | | | | | | | | | |
|----------------|---|-----------|---|---|---|---|---|---|---|---|---|---|---|---|---|---|
| | | visit (k) | | | | | | | | | | | | | | |
| | | | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | |
| | | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| | | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 0 | 1 | 0 | 1 |
| | | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | 0 | 1 | 1 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| | | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| individual (i) | ↓ | | | | | | | | | | | | | | | |
| | | trap (j) | | | | | | | | | | | | | | |

Spatial Capture-Recapture (SCR)

A typical SCR data set therefore consists of:

- spatial locations of each trap - \mathbf{x}_j
- individual-by-trap/location spatial encounter histories – $\mathbf{y}_{i,j}$

Biologically: Observations $\mathbf{y}_{i,j}$ occur as a result of movement around an home range center and frequency of detection decreases with distance between trap and activity center \mathbf{s}_i

Statistically: Observations $\mathbf{y}_{i,j}$ are realizations of a probability distribution whose mean is a latent variable \mathbf{s}_i i.e. a random-effects model

Model for encounter probability (many exist):

$$y_{i,j} \sim \text{Binomial}(K, p_{i,j})$$

$$p_{i,j} = f(d[\mathbf{s}_i, \mathbf{x}_j])$$

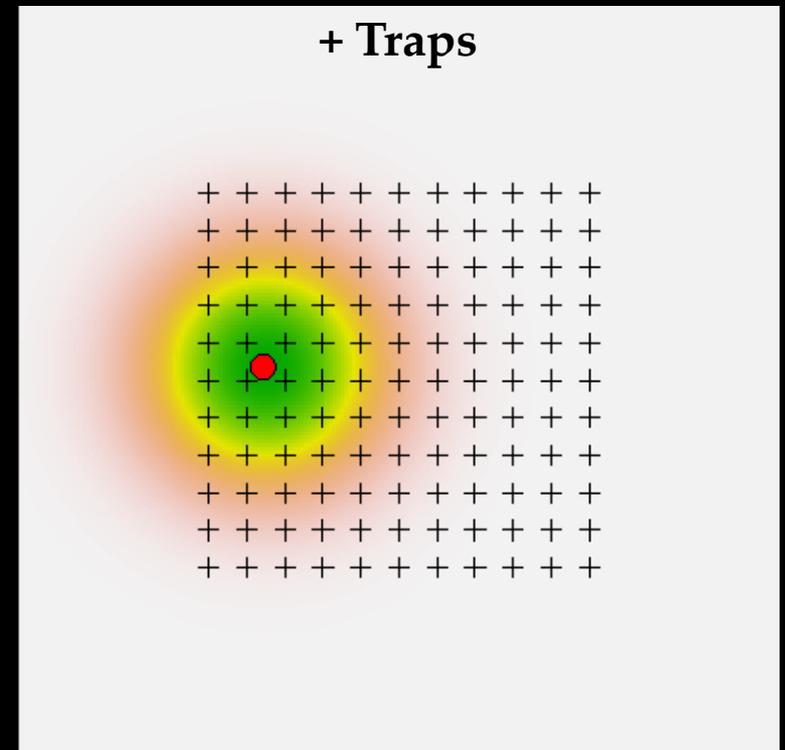
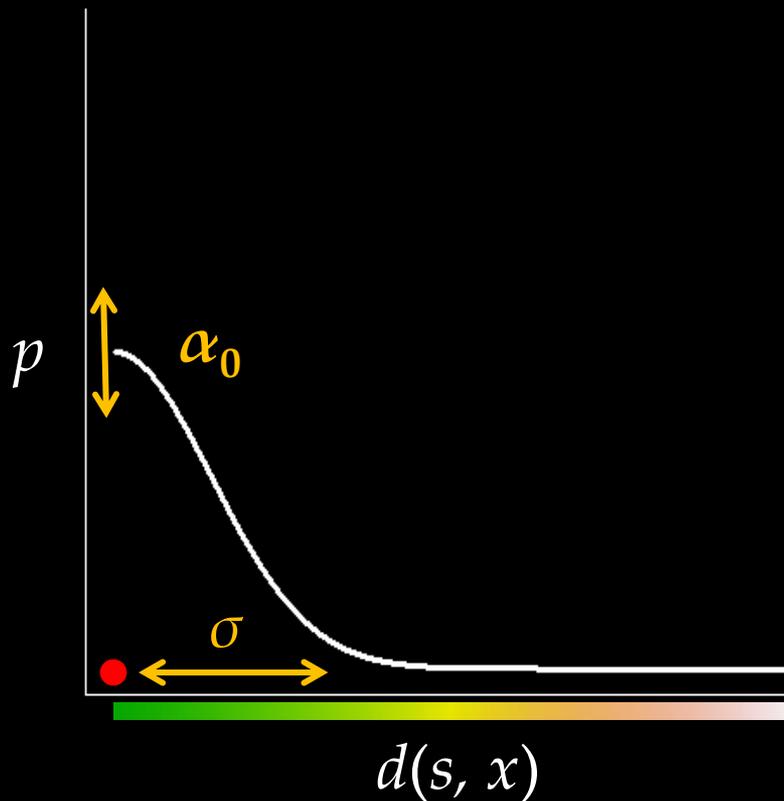
Modeling movement using SCR

Bivariate normal encounter model:

$$y_{i,j} \sim \text{Binomial}(K, p_{i,j})$$

$$p_{i,j} = \alpha_0 \exp(-\alpha_1 d[s_i, x_j]^2)$$

$$\alpha_1 = 1/(2\sigma^2)$$



Modeling movement using SCR [*poorly in some cases?*]

Bivariate normal encounter model:

$$y_{i,j} \sim \text{Binomial}(K, p_{i,j})$$

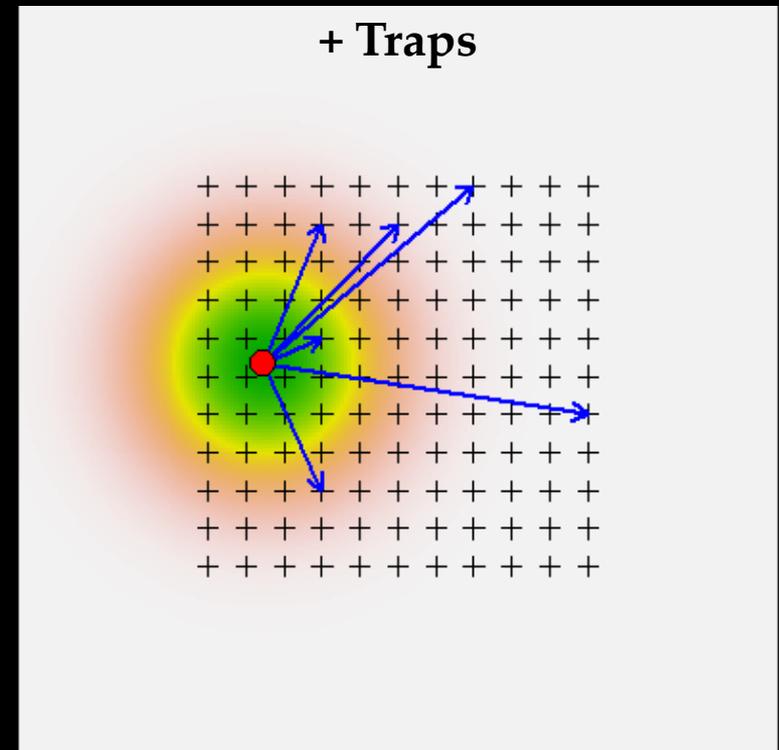
$$p_{i,j} = \alpha_0 \exp(-\alpha_1 d[s_i, x_j]^2)$$

$$\alpha_1 = 1/(2\sigma^2)$$

Euclidean distance:

- circular home range
- uniform landscape [use]

⇒ Biologically unrealistic



Modeling movement using SCR [*poorly in some cases?*]

Bivariate normal encounter model:

$$y_{i,j} \sim \text{Binomial}(K, p_{i,j})$$
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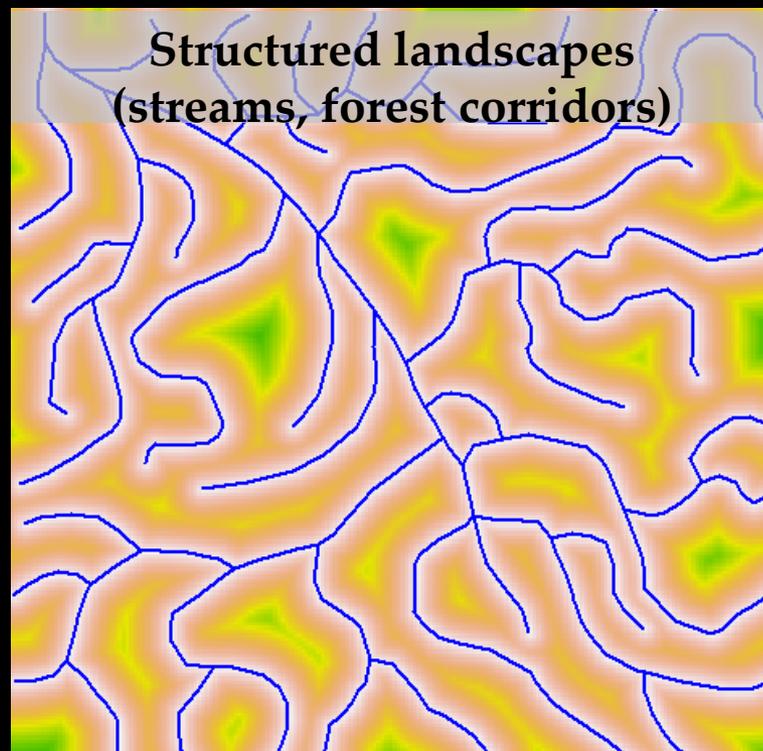
Euclidean distance:

- circular home range
- uniform landscape [use]

⇒ **Biologically unrealistic**

Movement is not equally likely
through all habitats:

- cost/resistance



Stream networks & riparian species – my motivation!

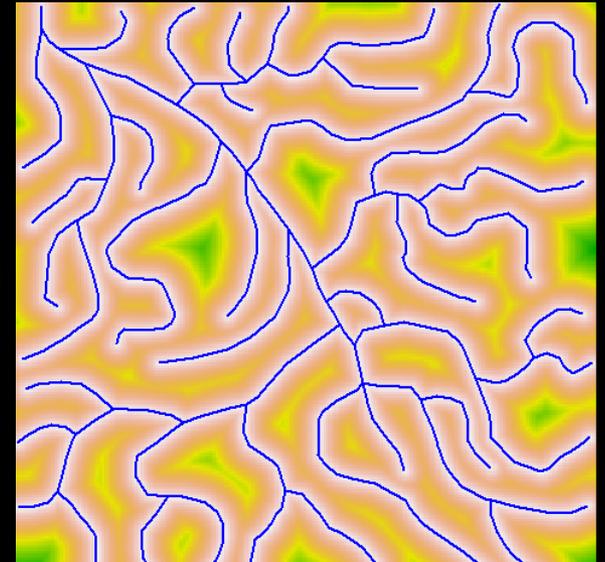
The American mink *Neovison vison*:

- economically important
- community regulator
- top predator (aquatic)
- indicators of ecosystem health



A perfect model system:

- semi-aquatic (∴ non-Euclid. movement)
- habitat specialist (∴ non-Euclid. movement)
- landscape (dist. to water) 'easy' to define

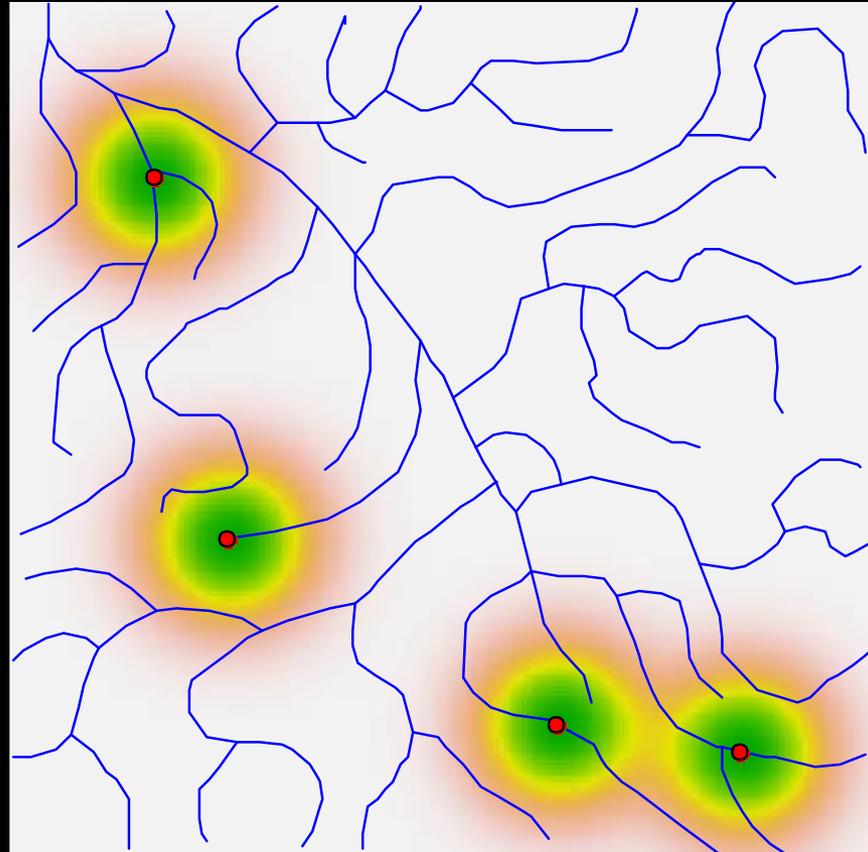


So, how should we measure distance?

Distance as the *what?* moves... 1

Three ways to measure distance:

- Euclidean distance - distance as the 'crow flies'

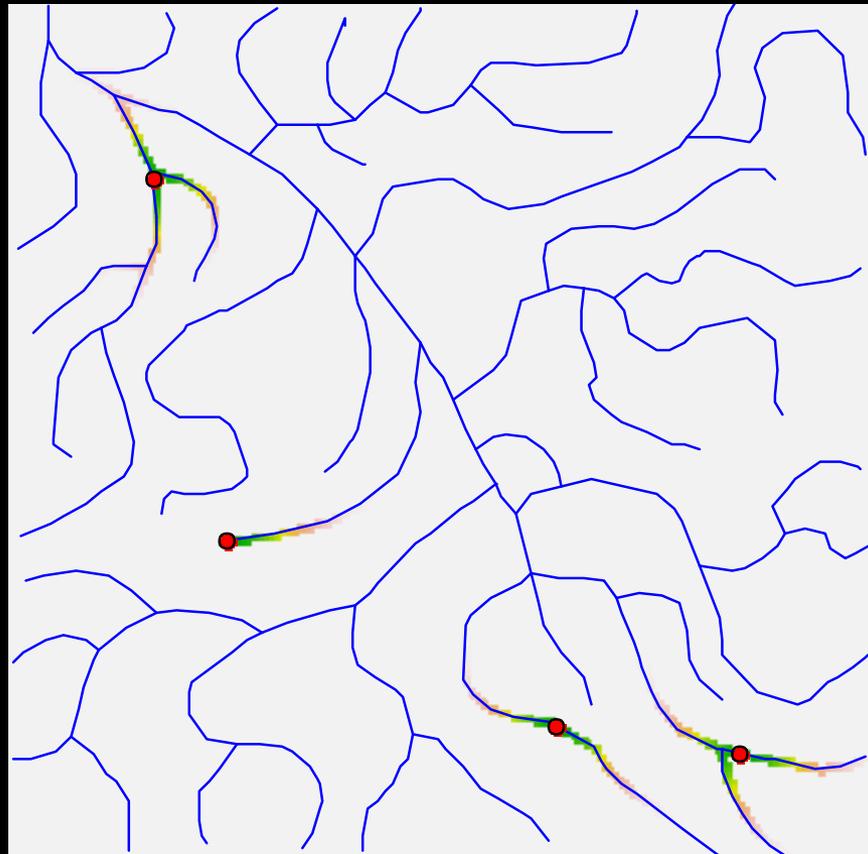
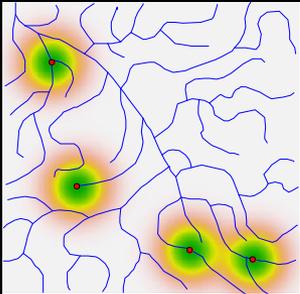


Distance as the *what?* moves... 1

Three ways to measure distance:

- River/stream distance - distance as the 'fish swims'

Distance as the
'crow flies'

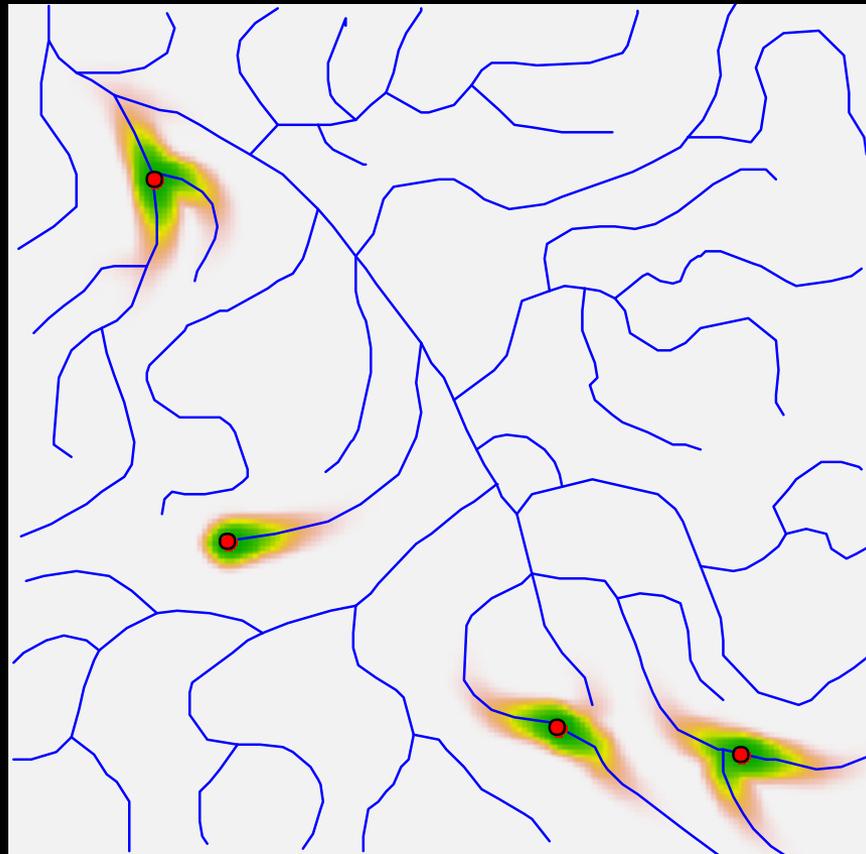
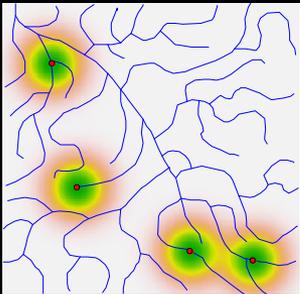


Distance as the *what?* moves... 1

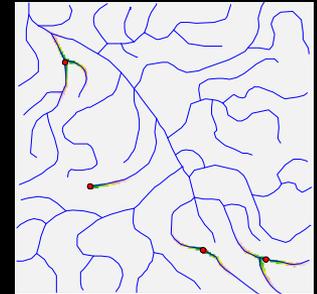
Three ways to measure distance:

- 'Cost weighted' distance - distance as the 'mink moves'

Distance as the
'crow flies'

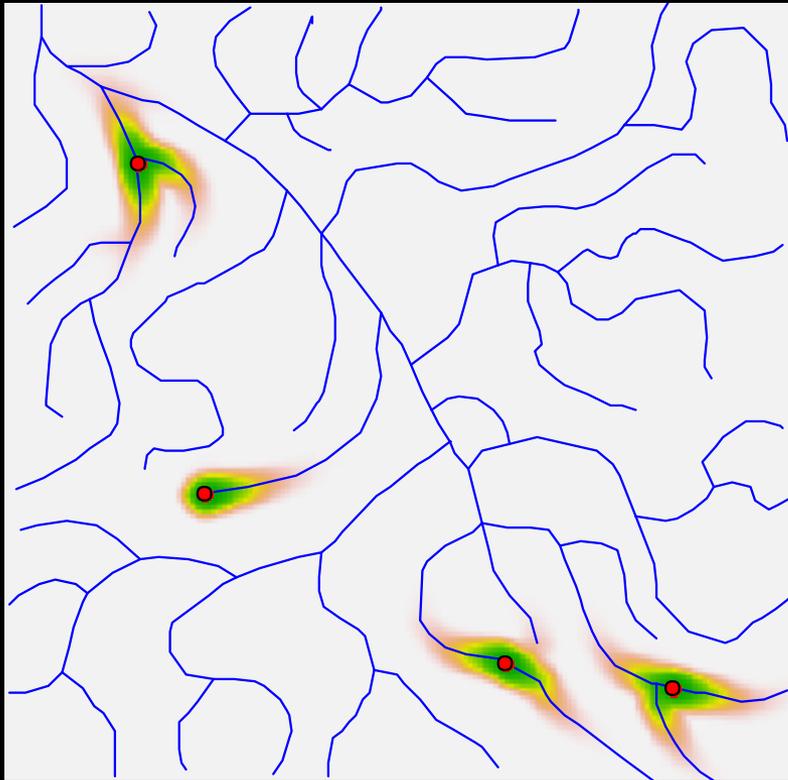


Distance as the
'fish swims'



Distance as the *MINK* moves... 1

Cost weighted 'mink moves' distance:



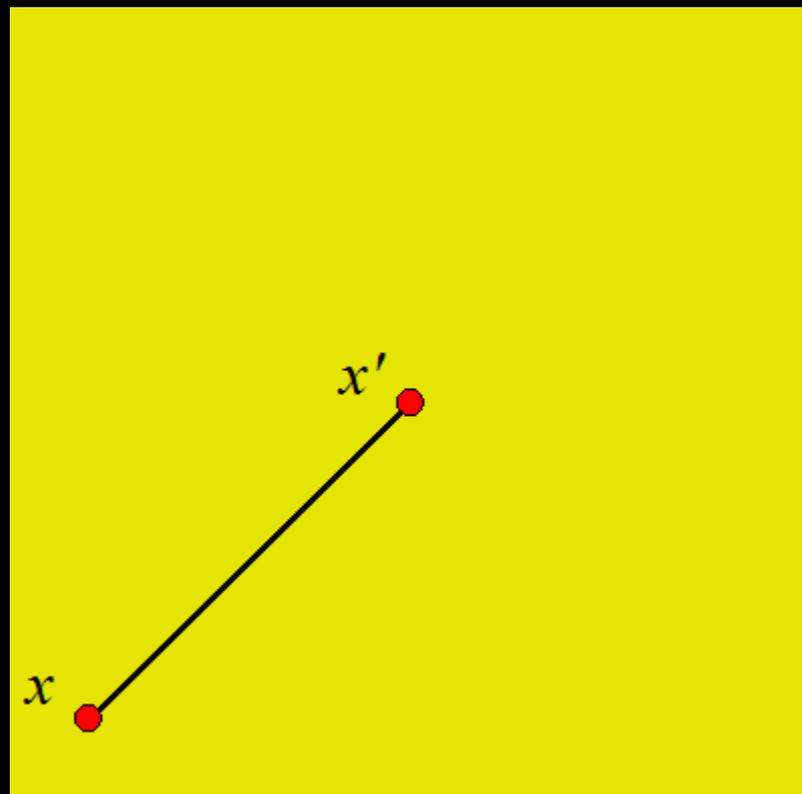
- Spatially varying landscape resistance (*distance to water*)
- Usually arbitrarily defined
- Use observations of movements to *estimate* resistance, *r*
[*within SCR framework!*]

Estimating landscape resistance using SCR

Gaussian encounter model:

$$y_{x,x'} \sim \text{Binomial}(K, p_{x,x'})$$

$$p_{x,x'} = \alpha_0 \exp(-\alpha_1 d[x, x']^2)$$



Royle *et al.*, 2013

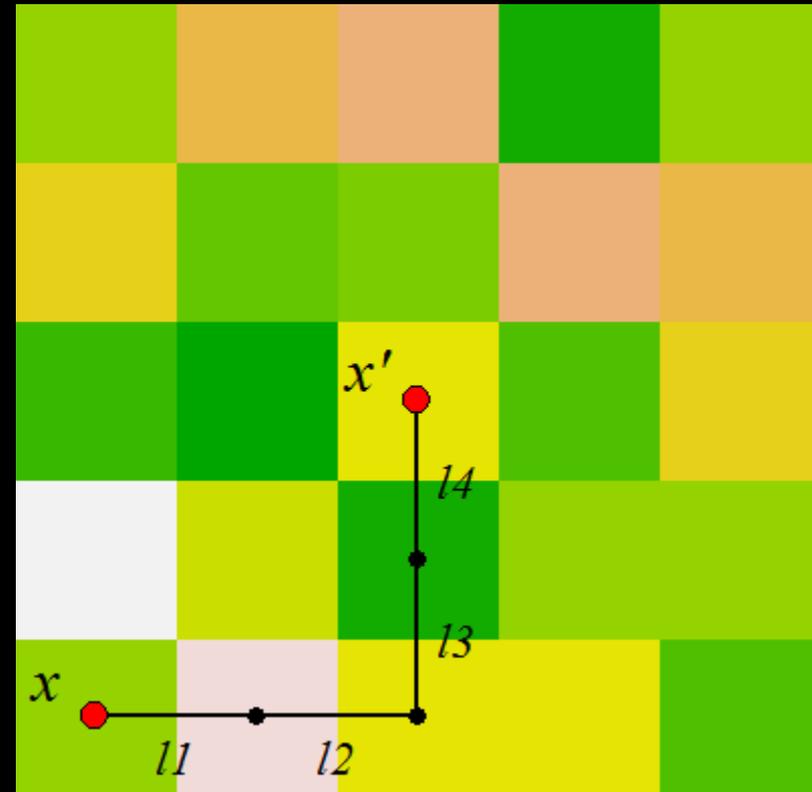
Estimating landscape resistance using SCR

Gaussian encounter model:

$$y_{x,x'} \sim \text{Binomial}(K, p_{x,x'})$$

$$p_{x,x'} = \alpha_0 \exp(-\alpha_1 d_{lcp}[x, x']^2)$$

$$d(x, x') = \sum_{i=1}^{m-1} \text{cost}(\mathbf{l}_i, \mathbf{l}_{i+1}) \|\mathbf{l}_i - \mathbf{l}_{i+1}\|$$



Royle *et al.*, 2013

Estimating landscape resistance using SCR

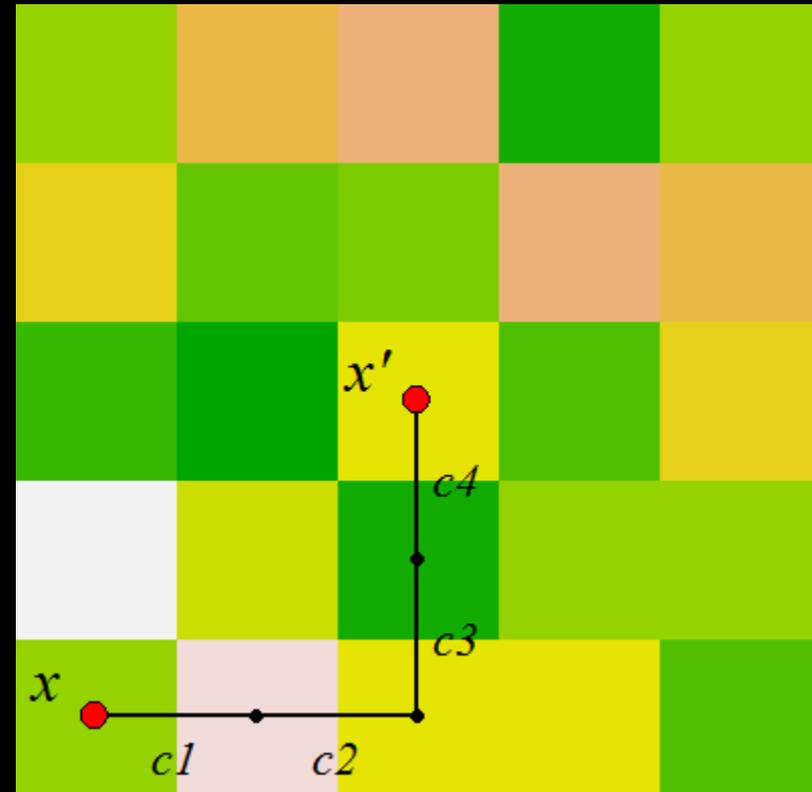
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$$d(x, x') = \sum_{i=1}^{m-1} \text{cost}(\mathbf{l}_i, \mathbf{l}_{i+1}) \|\mathbf{l}_i - \mathbf{l}_{i+1}\|$$

$$\text{cost}(\mathbf{l}_i, \mathbf{l}_{i+1}) = f[\mathbf{r}, z(\mathbf{l}_i) - z(\mathbf{l}_{i+1})]$$



Royle *et al.*, 2013

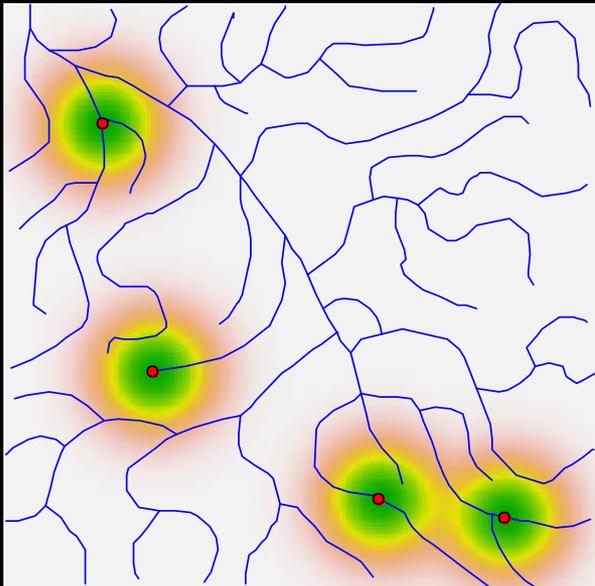
The cost function - learning about the space-use

$$\log[\text{cost}(x, x')] = r \frac{z(x) + z(x')}{2}$$

r provides information about space use patterns and behavior

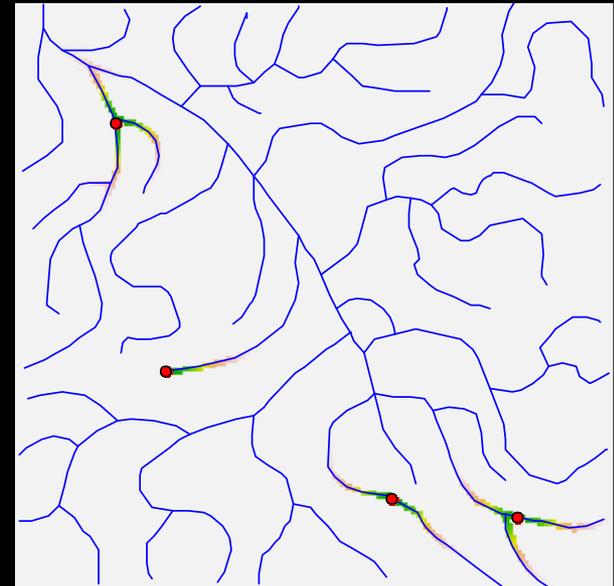
Euclidean distance
(‘crow flies’)

$$r = 0$$



Stream distance
(‘fish swims’)

$$r \rightarrow \infty$$



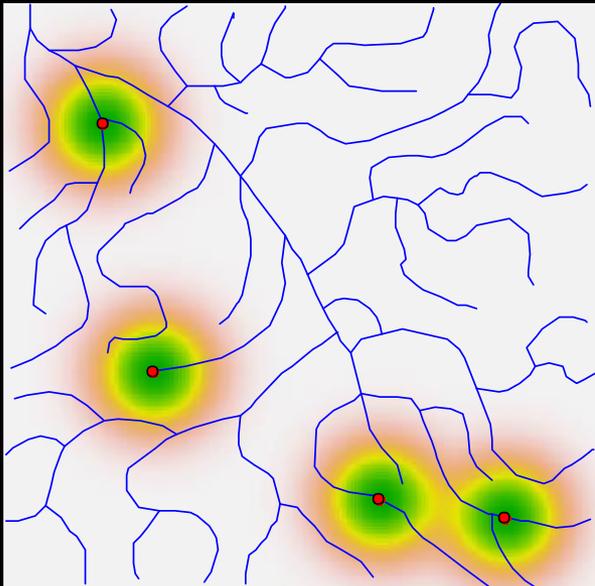
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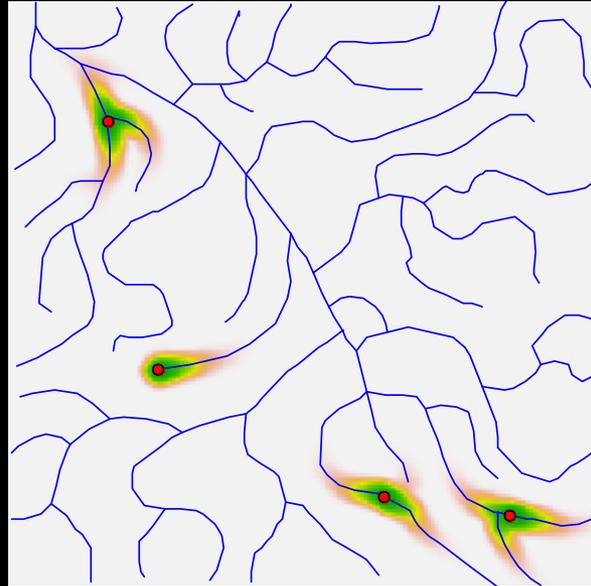
Euclidean distance
(‘crow flies’)

$$r = 0$$



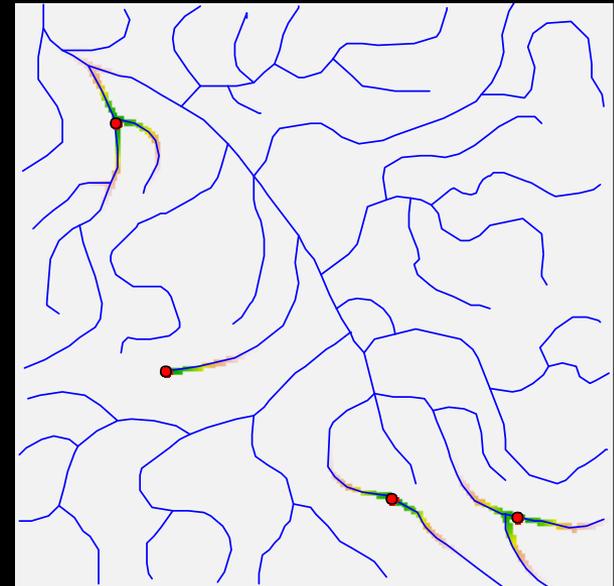
Ecological distance
(‘mink moves’)

$$0 < r < \infty$$



Stream distance
(‘fish swims’)

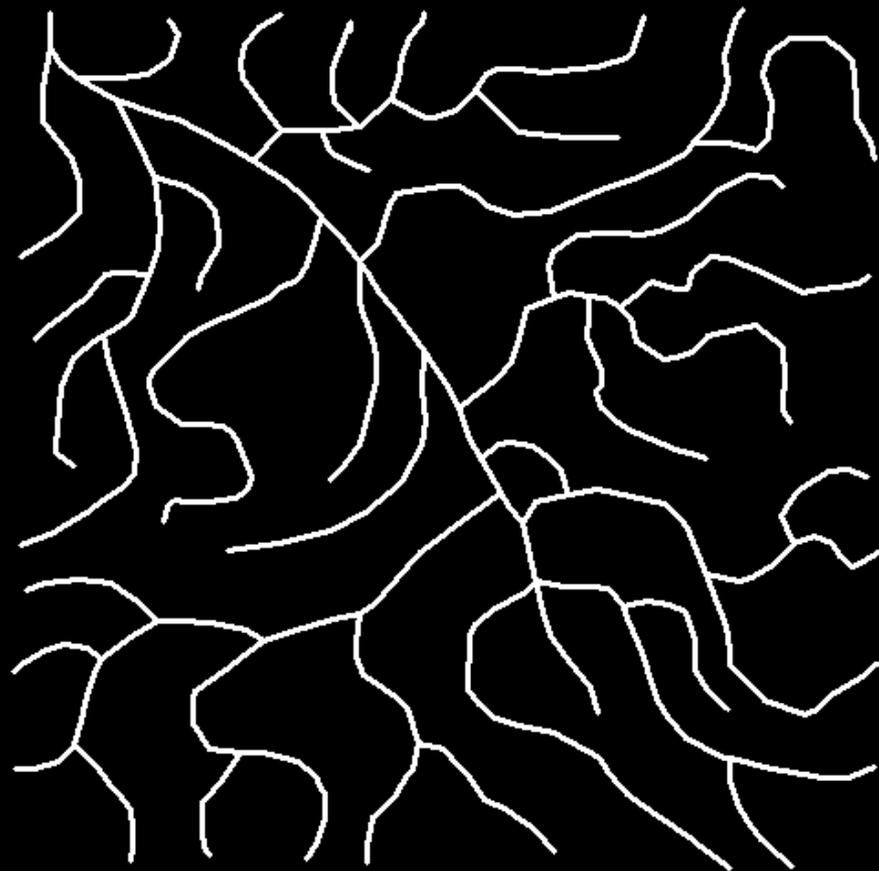
$$r \rightarrow \infty$$



Testing the theory:
Mink-like simulation study

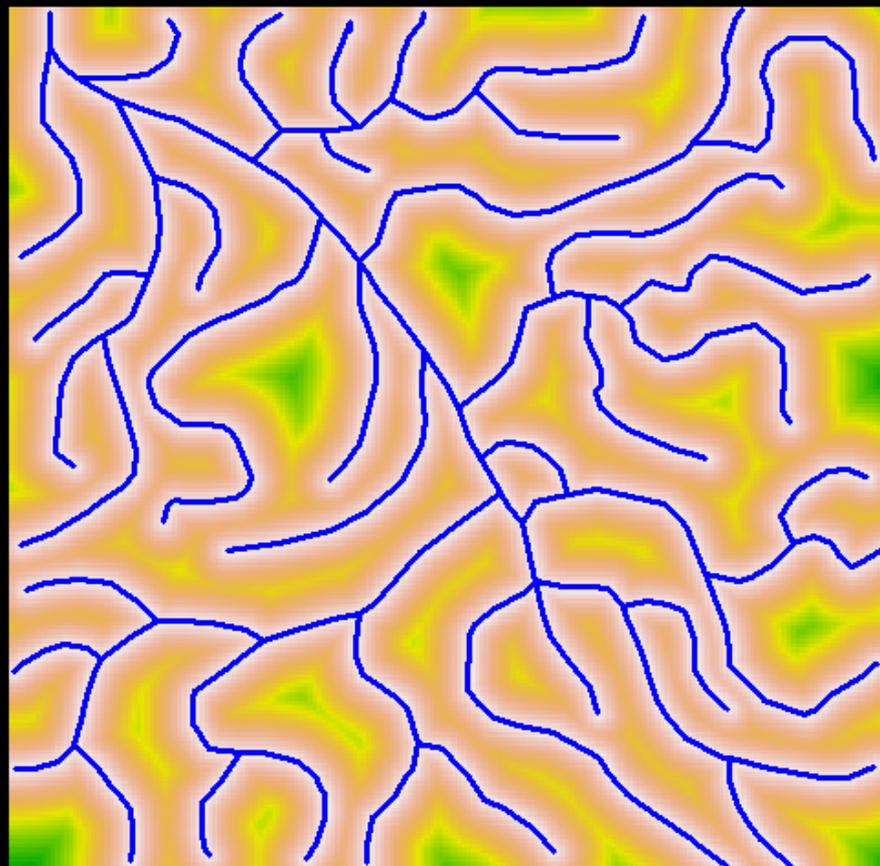
Mink-like simulation study - Data

- water layer



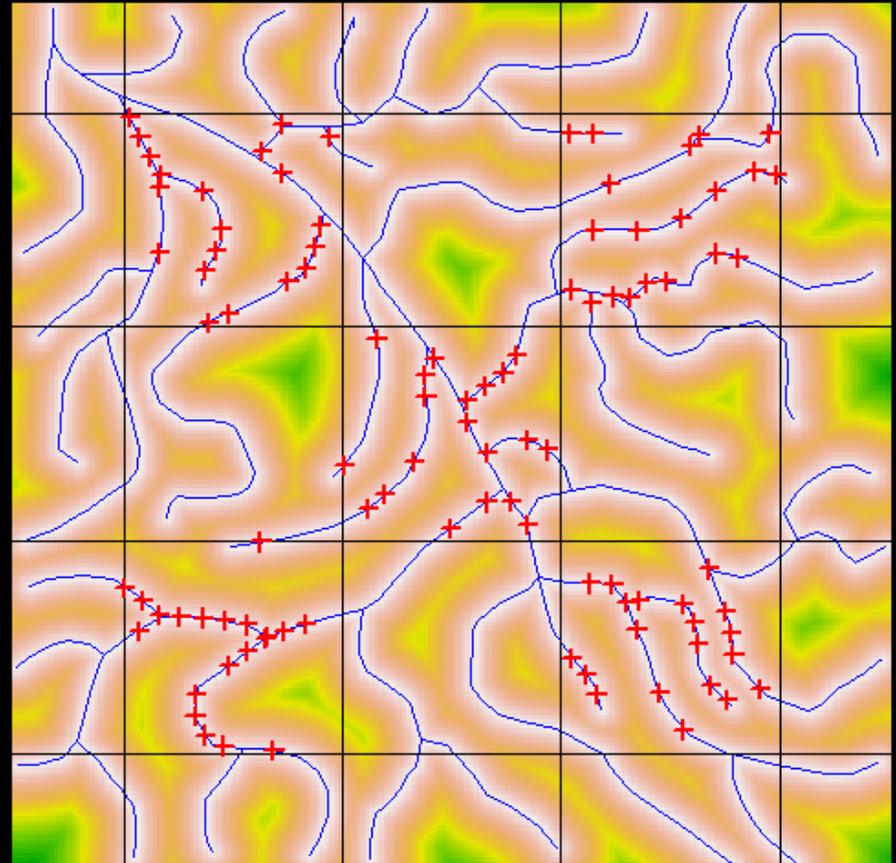
Mink-like simulation study - Data

- water layer
- distance to water covariate
(200m x 200m grid cells)



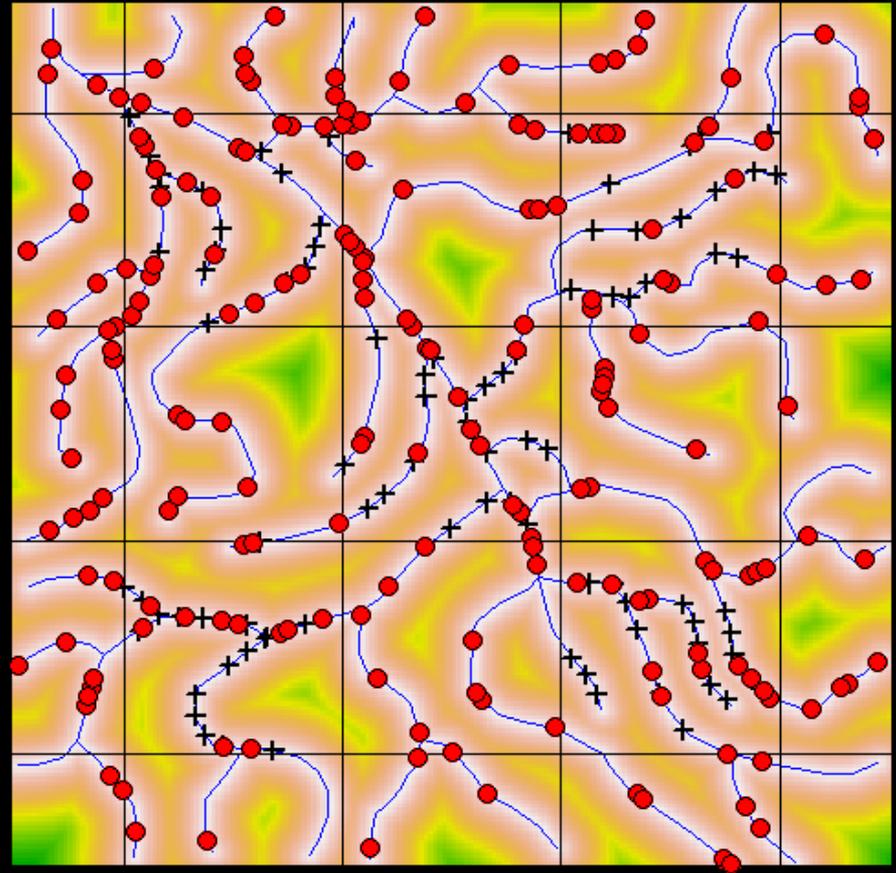
Mink-like simulation study - Data

- water layer
- distance to water covariate
(200m x 200m grid cells)
- 100 traps (5 clusters of 20)



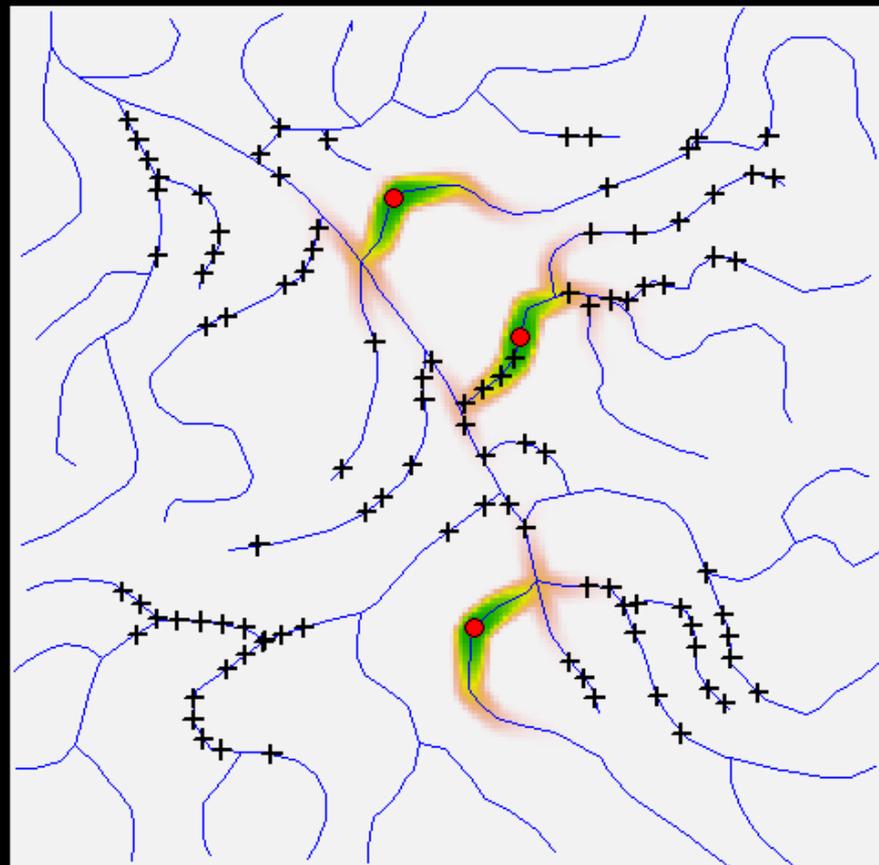
Mink-like simulation study - Data

- water layer
- distance to water covariate
(200m x 200m grid cells)
- 100 traps (5 clusters of 20)
- **$N = 200$ mink located along the water way**



Mink-like simulation study - Data

- water layer
- distance to water covariate
(200m x 200m grid cells)
- 100 traps (5 clusters of 20)
- $N = 200$ mink located along the water way
- generate spatial encounter histories using:
 $\alpha_0 = 0.38; \sigma = 0.05; r = 2.5$

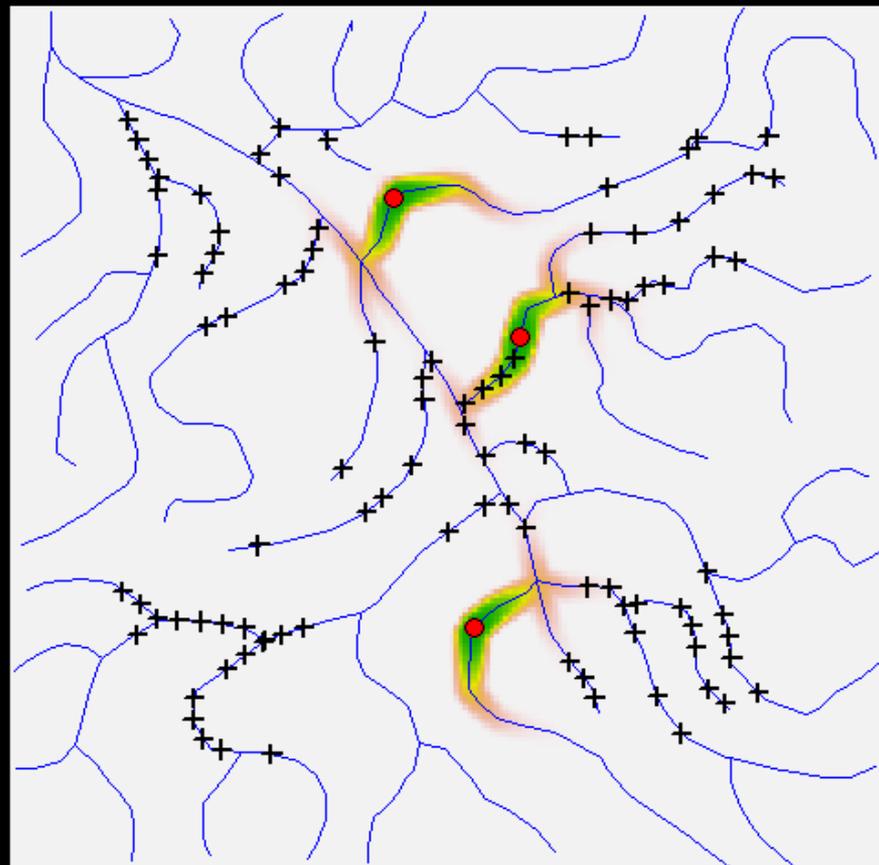


Mink-like simulation study - Data

- water layer
- distance to water covariate
(200m x 200m grid cells)
- 100 traps (5 clusters of 20)
- $N = 200$ mink located along the water way
- generate spatial encounter histories using:

$$\alpha_0 = 0.38; \sigma = 0.05; r = 2.5$$

- Fit the model (repeat 253 times)



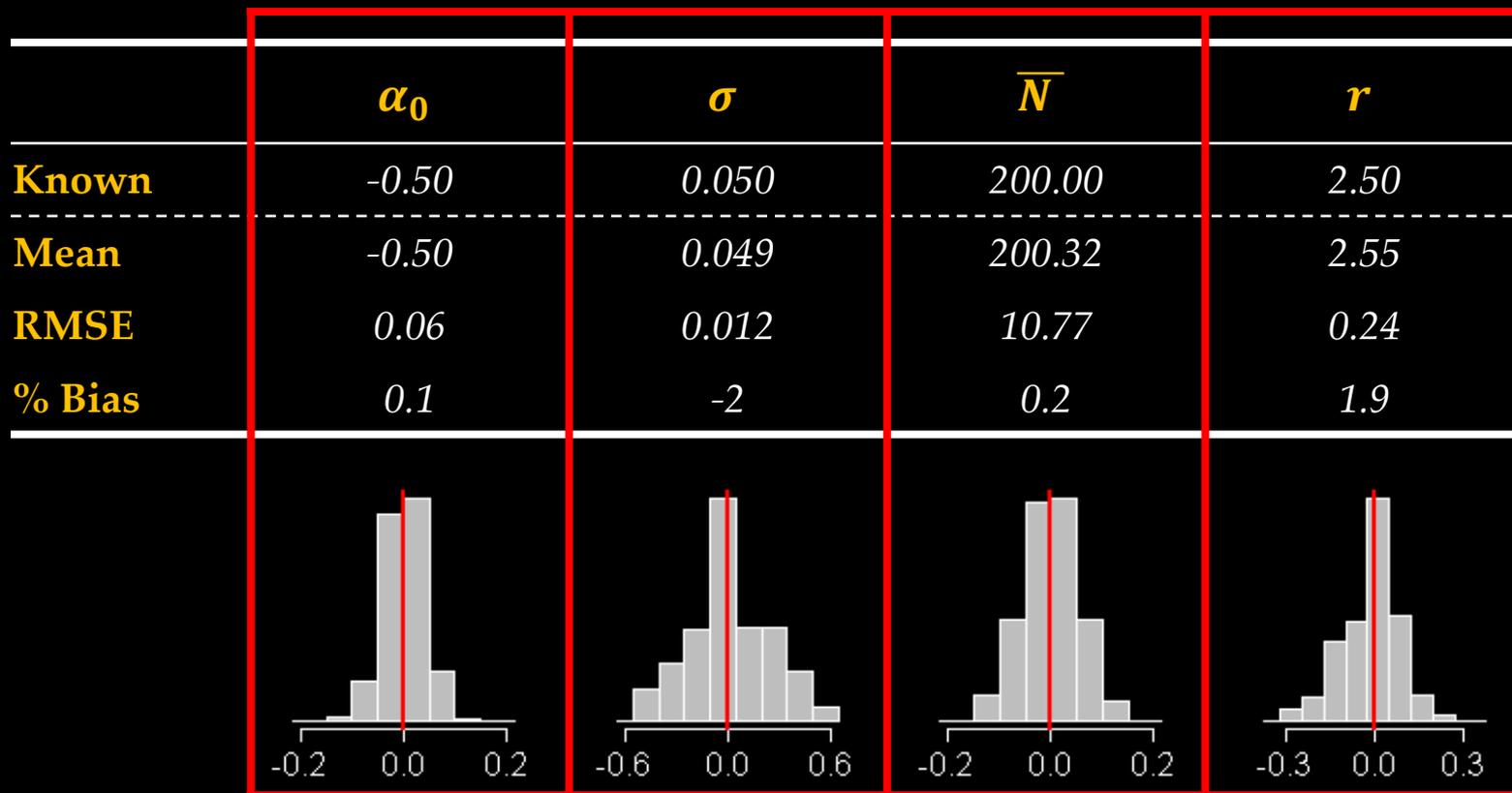
Mink-like simulation study - Results

1. Retrieving known parameter values using the '*mink moves*' ecological distance model:

Statistical properties of $\theta = [\alpha_0, \sigma, N, r]$

Mink-like simulation study - Results

Estimating parameters of known values $\theta = [\alpha_0, \sigma, \bar{N}, r]$



$$(\hat{\theta} - \theta) / \theta$$

Mink-like simulation study - Results

1. Retrieving known parameter values using the '*mink moves*' ecological distance model:

✓ $\theta = [\alpha_0, \sigma, N, r]$ recovered with little bias

2. Compare the 'performance' of two competing models:

$M_{ecological}$ – '*mink moves*' model estimating landscape resistance

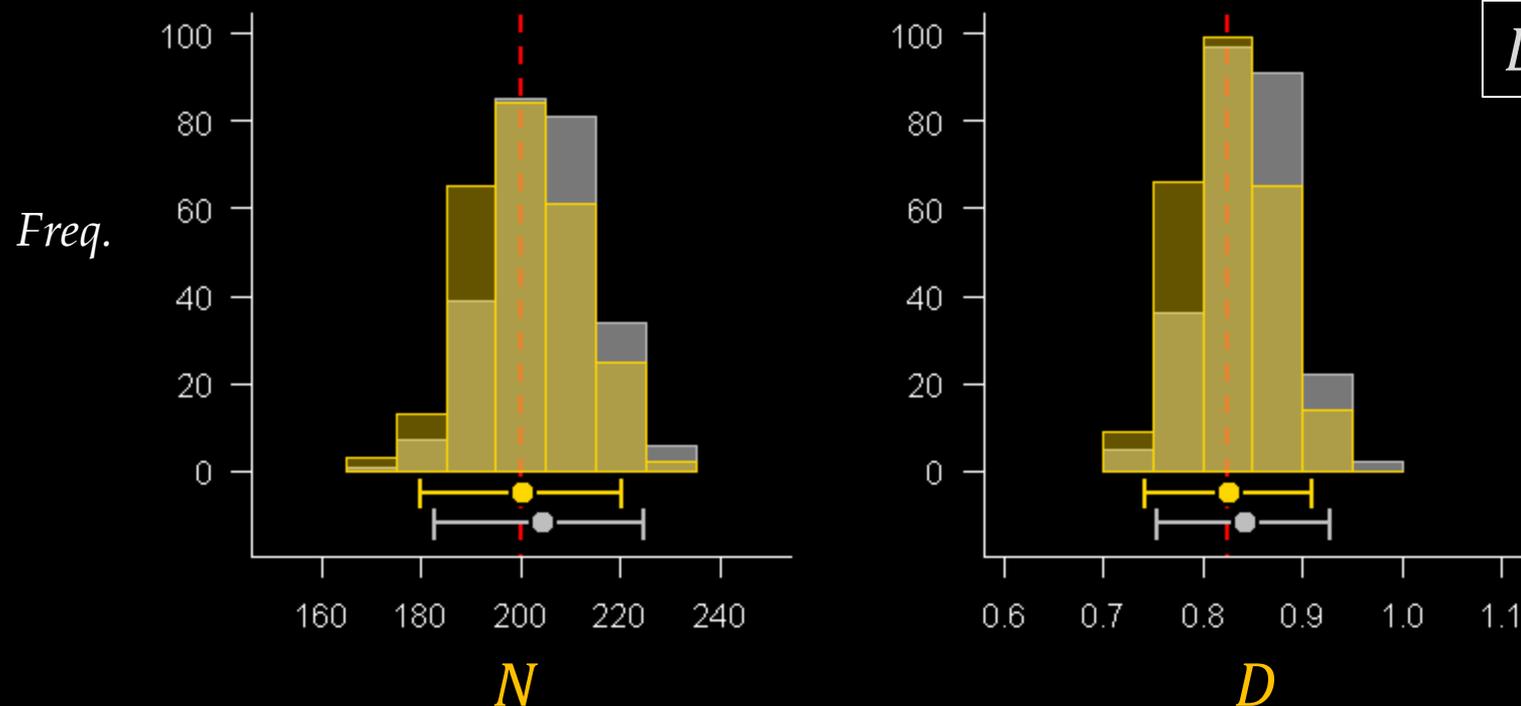
vs.

$M_{euclidean}$ – '*crow flies*' model assuming stationary home ranges

Mink-like simulation study - Results

Comparing estimates of N (and D) using Euclidean *vs.* ecological distance:

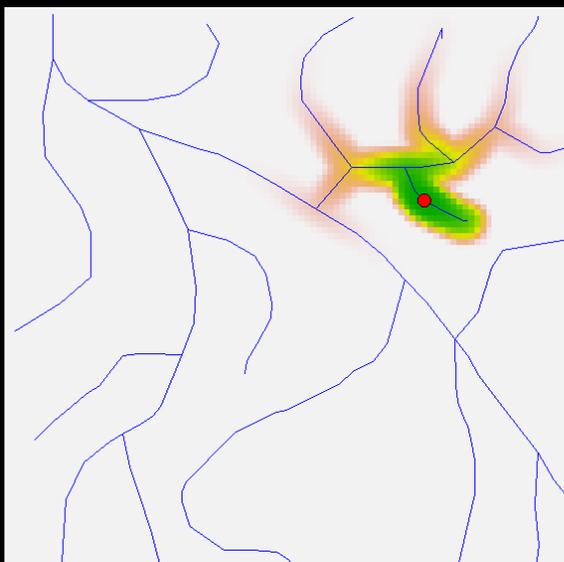
| % bias in N (D) | |
|-----------------------|-----|
| Euclidean | 2.2 |
| Ecological | 0.2 |



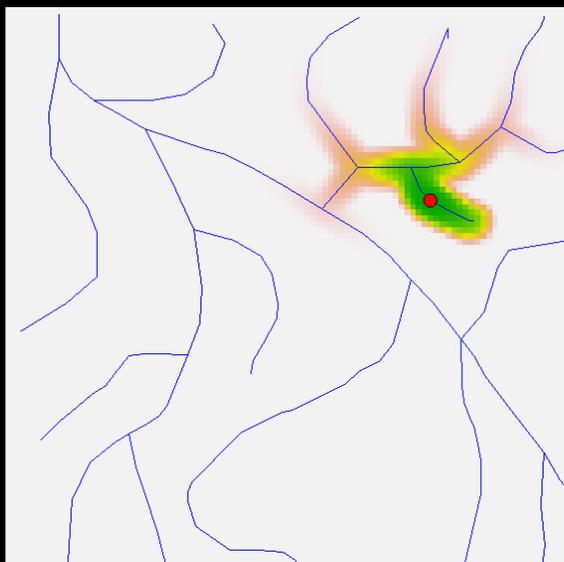
Mink-like simulation study - Results

Comparing space-use patterns (home range *shapes*) assuming
Euclidean *vs.* ecological distance:

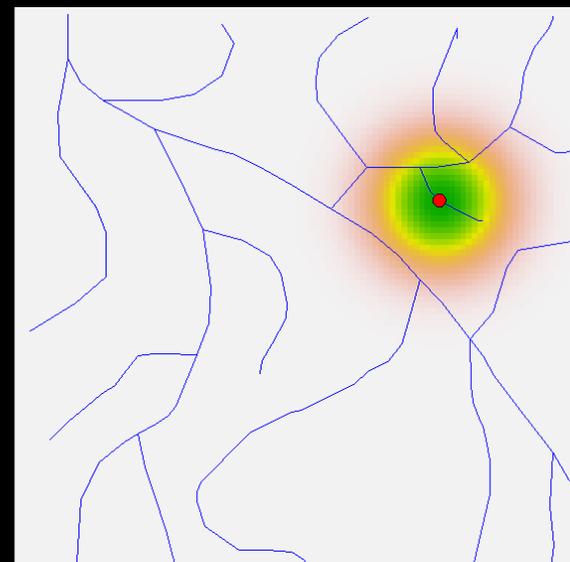
Simulated space-use
data ('truth')



Estimated using
'ecological distance'



Estimated using
'Euclidean distance'



Mink-like simulation study - Models

1. Retrieving known parameter values using the '*mink moves*' ecological distance model:

✓ Unbiased estimators of $\theta = [\alpha_0, \sigma, N, r]$

2. Compare the 'performance' of two competing models:

✓ $M_{ecological}$ – '*mink moves*' model estimating landscape resistance
vs.
 $M_{euclidean}$ – '*crow flies*' model assuming stationary home ranges

Testing the theory:

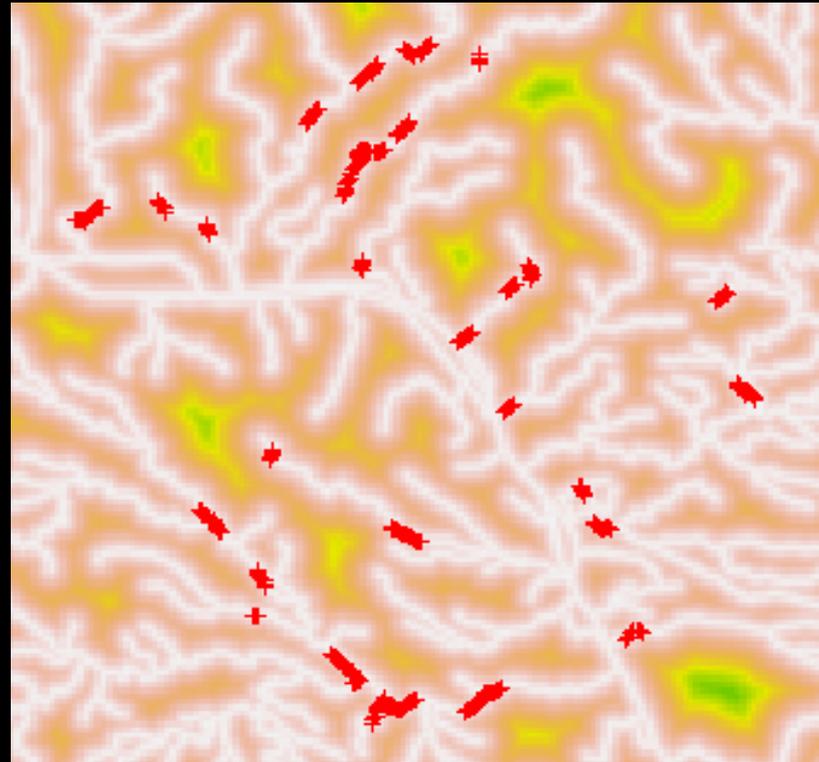
~~Mink-like simulation study~~

Application to a population of
American mink

Mink study - Data

- Study area = 293.04 km² (515km of stream)
- Scat detection dogs
- Genetic identification of individuals
- 25 transects = 255 'effective traps'
- 37 unique individuals

| Frequency | 1 | 2 | 3 | 4 | 5 | 6 | 7 |
|--------------------------------------|----|---|---|---|---|---|---|
| # individuals (in <i>n</i> traps) | 24 | 8 | 3 | 1 | | | 1 |



Mink study - Results

1. Compare the two competing models:

$M_{ecological}$ – '*mink moves*' model estimating landscape resistance

vs.

$M_{euclidean}$ – '*crow flies*' model assuming stationary home ranges

Mink study - Results

1. Compare the two competing models:

$M_{ecological}$ – ‘mink moves’ model estimating landscape resistance

vs.

$M_{euclidean}$ – ‘crow flies’ model assuming stationary home ranges

Model fit (AIC)

| | N_{params} | AIC | Δ AIC | Density (se) |
|------------------|--------------|--------|--------------|--------------|
| $M_{ecological}$ | 4 | 366.59 | - | 1.06 (0.50) |
| $M_{euclidean}$ | 3 | 372.70 | 6.11 | 1.08 (0.54) |

Mink study - Results

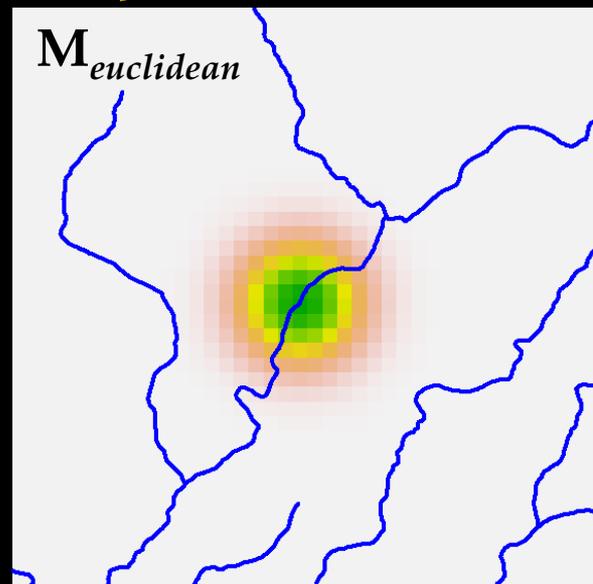
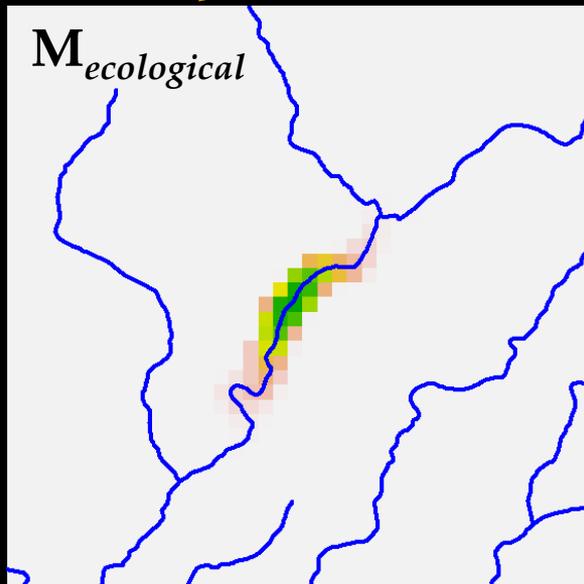
1. Compare the two competing models:

$M_{ecological}$ – ‘*mink moves*’ model estimating landscape resistance

vs.

$M_{euclidean}$ – ‘*crow flies*’ model assuming stationary home ranges

Space-use/home range shape: $r = 20.35$



Mink study - Results

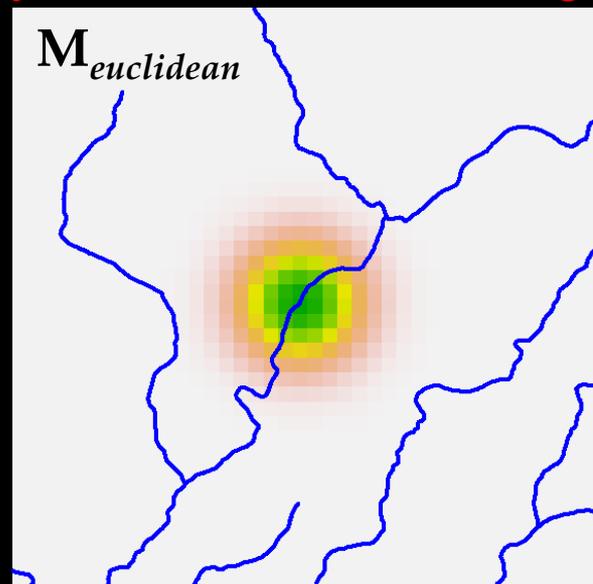
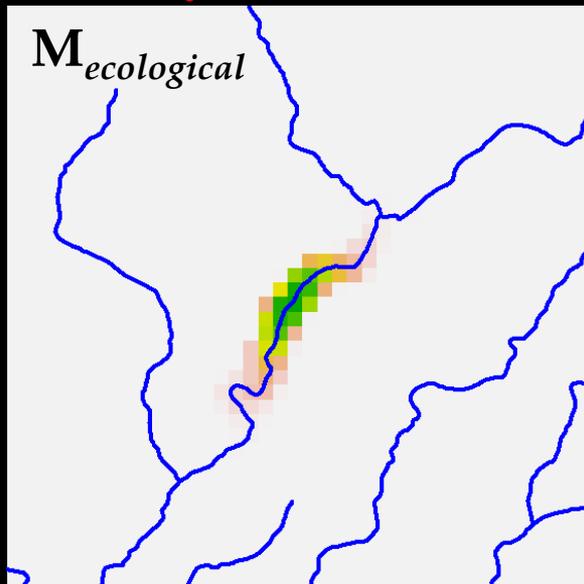
1. Compare the two competing models:

$M_{ecological}$ – ‘*mink moves*’ model estimating landscape resistance

vs.

$M_{euclidean}$ – ‘*crow flies*’ model assuming stationary home ranges

7 x more ‘costly’ to move 100m away from water than along water



Mink study - Results

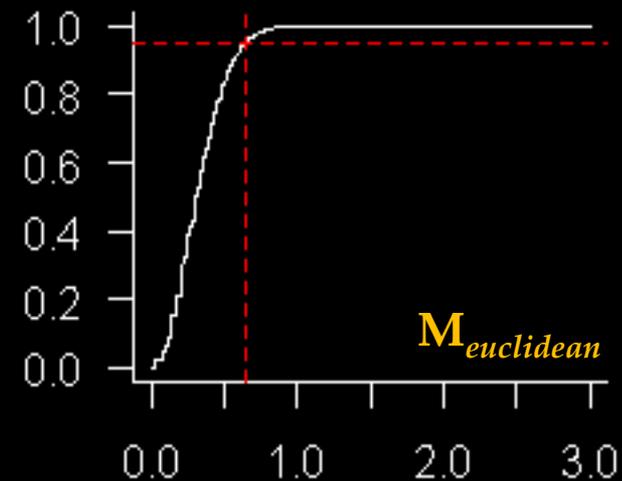
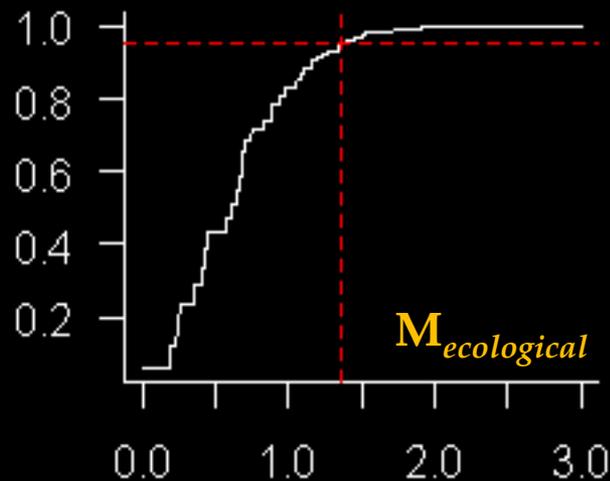
1. Compare the Compare the two competing models:

$M_{ecological}$ – ‘*mink moves*’ model estimating landscape resistance

vs.

$M_{euclidean}$ – ‘*crow flies*’ model assuming stationary home ranges

95% Home range size



Mink study - Results

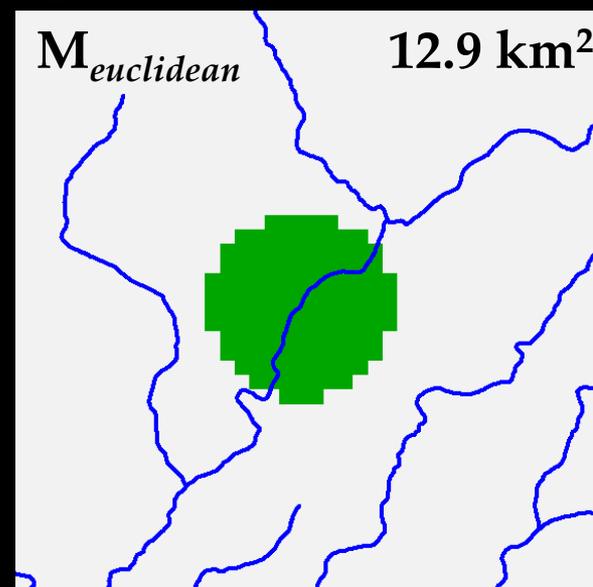
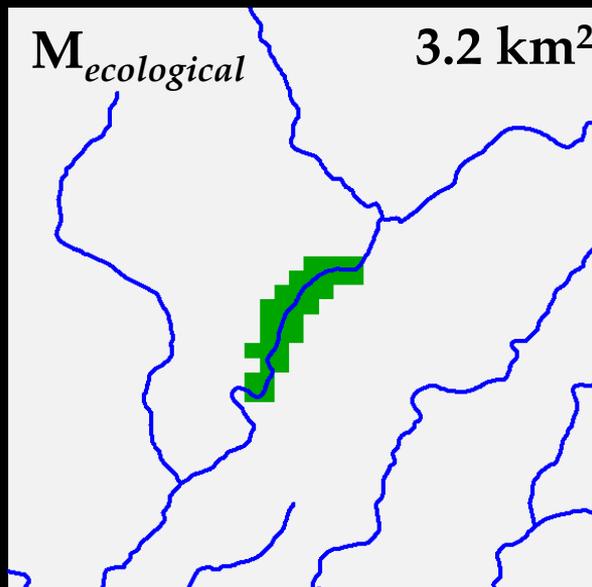
1. Compare the 'performance' of two competing models:

$M_{ecological}$ – '*mink moves*' model estimating landscape resistance

vs.

$M_{euclidean}$ – '*crow flies*' model assuming stationary home ranges

95% Home range size



Alternative distance measures and SCR... 1

Advantages of measuring *ecological distance*:

- relax the Euclidean assumptions of SCR methods
- no bias in estimators of abundance/density BUT
 - estimation of landscape resistance parameter
 - shape/size of irregular home-ranges/space-use

